Lecture 13. (Sketch.)

Homework was due today. [Some homework solutions discussed in class.] 1. Smoothness, sparsification, and the Maurey Lemma.

Fix any $z \in \mathbb{R}^d$ with $||z|| \le R$; GD with $w_0 := 0$ gives us $w_t := -\frac{1}{\beta} \sum_{i < t} \nabla f(w_i)$ with

$$f(w_t) \leq f(z) + \frac{\beta R^2}{2t}$$

Speaking vaguely (but making things precise momentarily), if $\nabla f(w_i)$ is "simple", then so is w_t (by induction), and we've given the existence of "simple" approximate optima to f.

Remark.

Never underestimate the power of simply writing down a gradient on paper.

• In the least squares case $f(w) := ||Xw - y||^2/2$ with $w_0 = 0$,

$$w_t := -\frac{1}{\beta} \sum_{i < t} \nabla f(w_i) = X^\top \left(-\frac{1}{\beta} \sum_{i < t} (Xw_i - y) \right);$$

i.e., $w_t \in im(X^{\top}) = ker(X)^{\perp}$; amongst other things, this implies w_t converges to the minimum norm solution.

In the case of neural networks, a few recent results crucially rely upon simply writing down the gradient and staring at it a certain way. **Lemma (Maurey).** Let β -smooth f and matrix $V \in \mathbb{R}^{d \times n}$ be given. For any $\alpha \in \Delta_n$, and any integer k, $\exists \hat{\alpha} \in \Delta_n \cap \mathbb{Z}^n / k$ with

$$f(V\hat{lpha}) \leq f(Vlpha) + rac{eta}{2k} \max_{i} \|V_{:,i}\|^2.$$

In particular, $\forall \alpha \in \Delta_n$, integer k, $\exists \hat{\alpha} \in \Delta_n \cap \mathbb{Z}^n / k$ satisfies

$$\|V\alpha - V\hat{\alpha}\|^2 \leq \frac{1}{k} \max_i \|V_{:,i}\|^2.$$

Remarks.

▶ Note that $\hat{\alpha} \in \Delta_n \cap \mathbb{Z}^n / k$ is *k*-sparse:

$$1 = \sum_{i=1}^{n} \hat{\alpha}_{i} \ge \sum_{i=1}^{n} \frac{1}{k} \mathbb{1} \left[\hat{\alpha}_{i} \ge \frac{1}{k} \right] = \sum_{i=1}^{n} \frac{1}{k} \mathbb{1} \left[\hat{\alpha}_{i} > 0 \right] = \frac{1}{k} \left| \{i : \hat{\alpha}_{i} > 0\} \right|.$$

- This lemma highlights another power of smoothness: it allows us to sparsify convex hulls! We'll use this property in the statistical/generalization part of the class.
- It's also used in a neural network uniform approximation proof Barron (1993).

Remarks (continued).

Another interpretation of the result: for any x ∈ V∆_n, there exists x̂ ∈ V∆_n which is k-sparse and satisfies

$$||x - \hat{x}||^2 \le \frac{1}{k} \max_i ||V_{:,i}||^2.$$

This has no dependence on the dimensions of V, but only the norms of its columns!

To highlight this lack of dimension dependence, consider a set U with sup_{v∈U} ||v|| ≤ R < ∞ (but potentially |U| = ∞). For any x ∈ cl(conv(U)) and ε > 0, by definition, there exists a subset (u₁,..., u_n) and α ∈ Δ_n with

$$\|x - x_n\| \le \epsilon$$
 where $x_n := \sum_{i=1}^n \alpha_i u_i$

Now we can apply the Maurey Lemma to x_n , and obtain x_k which is k-sparse with

$$||x_n - x_k||^2 \le \frac{R^2}{k}, \qquad ||x - x_k||^2 \le 2\epsilon^2 + \frac{2R^2}{k}.$$

Proof (continued).

Thus

$$\mathbb{E} \| \mathbf{V}\alpha - \mathbf{V}\mathbf{Y} \|^2 \leq \frac{1}{k} \|\alpha\|_1 \max_i \|\mathbf{V}_{:,i}\|^2.$$

By the probabilistic method (min is at most the expectation), there exists a $y_0 \in \Delta_n \cap \mathbb{Z}^n/k$ satisfying this bound, which gives the second part of the lemma. For the first part, since f is β -smooth,

$$egin{split} \mathbb{E}f(VY) &\leq \mathbb{E}\left(f(Vlpha) + \langle
abla f(Vlpha), VY - Vlpha
angle + rac{eta}{2} \|Vlpha - VY\|^2
ight) \ &\leq f(Vlpha) + 0 + rac{eta}{2k}\max_i \|V_{:,i}\|^2, \end{split}$$

which now (by the probabilistic method) gives a y_1 satisfying the first part of the theorem.

Note. We did not use a single y_0 for both parts.

Proof. Let β -smooth f, $\alpha \in \Delta_n$, integer k be given. Define r.v. X with $\Pr[X = \mathbf{e}_i] = \alpha_i$, whereby

$$\mathbb{E}X = \sum_{i=1}^{n} \alpha_i \mathbf{e}_i = \alpha, \qquad \mathbb{E}VX = V\mathbb{E}X = V\alpha.$$

Let (X_1, \ldots, X_n) be k iid copies of X, define $Y := \sum_i X_i/k$ (thus again $\mathbb{E}Y = \alpha$ and $\mathbb{E}VY = V\alpha$), and

$$\mathbb{E} \| V\alpha - VY \|^{2} = \frac{1}{k^{2}} \mathbb{E} \left\langle \sum_{i=1}^{k} (V\alpha - VX_{i}), \sum_{j=1}^{k} (V\alpha - VX_{j}) \right\rangle$$
$$= \frac{1}{k^{2}} \mathbb{E} \left(\sum_{i=1}^{k} \| V\alpha - VX_{i} \|^{2} + \sum_{i \neq j} \langle V\alpha - VX_{i}, V\alpha - VX_{j} \rangle \right)$$
$$= \frac{1}{k} \mathbb{E} \| V\alpha - VX_{1} \|^{2} = \frac{1}{k} \mathbb{E} \left(\| V\alpha \|^{2} - 2 \langle VX_{1}, V\alpha \rangle + \| VX_{1} \|^{2} \right)$$
$$= \frac{1}{k} \left(\left(\sum_{i=1}^{n} \alpha_{i} \| V\mathbf{e}_{i} \|^{2} \right) - \| V\alpha \|^{2} \right) \leq \frac{1}{k} \| \alpha \|_{1} \max_{i} \| V\mathbf{e}_{i} \|^{2}.$$

2. Constructing sparse covers.

Natural greedy approach:

- 1. $w_0 := V \hat{\alpha}_0$ for some (sparse) $\hat{\alpha}_0 \in \Delta_n$.
- 2. For $i \in \{1, ..., t\}$:

2.1
$$u_i := \operatorname{arg\,min}_{v \in \{V \mathbf{e}_1, \dots, V \mathbf{e}_n\}} \langle w_{i-1} - V \alpha, v \rangle.$$

2.2
$$w_i := (1 - \eta_i) w_{i-1} + \eta_i u_i \in V\Delta_n$$
.

To generalize this, note $w_{i-1} - V\alpha = \nabla_w (w \mapsto ||w - V\alpha||^2/2)(w_{i-1}).$

Frank-Wolfe / conditional gradient method.

1. $w_0 \in S$. 2. For $i \in \{1, ..., t\}$: 2.1 $u_i := \arg \min_{v \in S} \langle \nabla f(w_{i-1}), v \rangle$. (Assume minimum exists.) 2.2 $w_i := (1 - \eta_i) w_{i-1} + \eta_i u_i$. Remark (constrained optimization).

Frank-Wolfe is performing optimization constrained to a set S.

- To do so, it must compute arg min_{v∈S} ⟨∇f(w_{i-1}), v⟩, which is a linear objective subject to a convex constraint.
- A standard competing approach, which we will discuss soon, is projected gradient descent, which must compute arg min_{v∈S} ||v − w||², a quadratic objective subject to a convex constraint.

Frank-Wolfe literature often focuses on this distinction, naming many examples where the former is more tractable than the latter. Personally, I have found Frank-Wolfe very easy and convenient to implement a number of times. It is nice that it never leaves the constraint set.

Remarks (continued).

 (Step size.) Using η_i := 1/i incurs a factor ln(t) in the bound. The weighting here can be shown inductively to satisfy

$$w_t := \frac{\sum_{i=1}^t i v_i}{\sum_{i=1}^t i} = \frac{2}{t(t+1)} \sum_{i=1}^t i v_i$$

which puts more wait on later choices, and is sometimes called "polynomial weighting".

▶ To simplify, let's consider $S := \{w : ||w||_2 \le 1\}$. Then

$$\mathbf{v} := -rac{
abla f(\mathbf{w})}{\|
abla f(\mathbf{w})\|}, \qquad \mathbf{w}' := \mathbf{w} - \eta \left(rac{
abla f(\mathbf{w})}{\|
abla f(\mathbf{w})\|} + \mathbf{w}
ight),$$

where the final "+w" is not present in gradient descent.

Theorem.

Suppose f is β -smooth and convex, S is closed and bounded with $D := \sup_{v,v' \in S} ||v - v'|| < \infty$. Let $(w_i)_{i \le t}$ be given by Frank-Wolfe with $\eta_i := 2/(i+1)$. Then

$$f(w_t) \leq f(z) + \frac{2\beta D^2}{t+1}.$$

Remark (Comparison to Maurey).

- To make the comparison, set $S := \{V\mathbf{e}_1, \dots, V\mathbf{e}_n\}$.
- Maurey was non-constructive, did not need f to be convex, and slightly tighten the constants in the bound (but that may be analytic coincidence).
- Maurey gave a discrete solution in V â with â ∈ Δ_n ∩ Zⁿ/k. Frank-wolfe had V α' where α' has support size at most k but is real-valued. The exact properties of α' will be discussed momentarily.

Remarks (continued).

► Recall the definition of dual norm:

$$\|s\|_* := rg\max\{\langle w, s
angle : \|w\| \le 1\}.$$

Consequently, if $S := \{w : ||w|| \le 1\}$ (now an arbitrary norm), then

$$v := rgmin_{v \ inS} \langle
abla f(w), v
angle$$

satisfies $\langle \nabla f(w), u \rangle = - \|\nabla f(w)\|_{*}$. (We might elaborate upon this sort of analysis in the homework.)

 (Stopping conditions.) We mentioned that duality gap is the best way to construct stopping conditions, but that it's generally computationally infeasible. In the case of Frank-Wolfe, it ends up being tractable and clean (we might have a homework problem on this). **Proof.** Let $w \in S$ and $\eta \in [0, 1]$ be arbitrary, and set $u := \arg \min\{\langle \nabla f(w), v \rangle \text{ and } w' := (1 - \eta)w + \eta u$. For any z,

$$egin{aligned} f(w')-f(z)&\leq f(w)-f(z)+\langle
abla f(w),\eta(u-w)
angle+rac{eta\eta^2\|u-w\|^2}{2}\ &\leq f(w)-f(z)+\eta\min_{v\in S}\left<
abla f(w),v-w
ight>+rac{eta\eta^2D^2}{2}\ &\leq f(w)-f(z)+\eta\left<
abla f(w),z-w
ight>+rac{eta\eta^2D^2}{2}\ &\leq f(w)-f(z)+\eta(f(z)-f(w))+rac{eta\eta^2D^2}{2}\ &\equiv (1-\eta)\left(f(w)-f(z)
ight)+rac{eta\eta^2D^2}{2}. \end{aligned}$$

Now consider i = 1; then $\eta_i = 2/(i + 1) = 1$, so the above gives

$$f(w_1)-f(z) \leq 0 + \frac{\beta\eta^2 D^2}{2} \leq \frac{2\beta D^2}{i+1}$$

Proof (continued).

When i > 1, the inductive hypothesis and preceding inequality together give

$$egin{aligned} f(w') - f(z) &\leq (1 - 2/(i+1)) \left(f(w) - f(z)
ight) + rac{2eta\eta^2 D^2}{(i+1)^2} \ &\leq (1 - 2/(i+1)) \left(rac{2eta D^2}{i}
ight) + rac{2eta\eta^2 D^2}{(i+1)^2} \ &\leq rac{2eta D^2}{i+1} \left(rac{i-1}{i} + rac{1}{i+1}
ight). \end{aligned}$$

References

Barron, Andrew R. 1993. "Universal Approximation Bounds for Superpositions of a Sigmoidal Function." *IEEE Transactions on Information Theory* 39 (3): 930–45.